05A-2185-6-L

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Westinghouse Electric Corporation

Air Arm Division

Friendship International Airport Box 746, Baltimore 3, Md. Telephone: 761-1000

November 13, 1962

Special Projects Office (ASZ-5) Plans and Programs Office Directorate of Production Wright-Patterson AFB. Ohio



SUBJECT: Contract AF 33(600)-40280, Reduction in Scope, Motion Compensation.
Westinghouse Ref. AAN-45196-20

- Reference (a): Westinghouse Letter dated 27 August 1962, subject: Contract AF 33(600)-40280, Program Extension.
- Enclosure (1): Three (3) copies Westinghouse Specification R-1916, Rev.
  A dated November 7, 1962 entitled "Antenna Angle and Motion
  Compensation, Follower Version".
- Enclosure (2): Three (3) copies Westinghouse Cost and Price Analysis, Form FE-777-1 dated Movember 12, 1962.

#### Gentlemen:

The proposal submitted by Reference (a) and which subsequently was incorporated in the Contract by Amendment No. 13, included design and fabrication effort necessary to achieve motion compensation by roll stabilizing the linear cross track accelerometers and by stabilizing the antennas for two systems with a total estimated cost of \$ 142,283. (Refer to Item I, Section B of Reference (a)). Becent technical discussions have indicated the desirability of your directly procurring the signal sources, servos and actuators required for such motion compensation in accordance with a performance specification to be furnished by Westinghouse. Under this approach Westinghouse proposes to provide:

- (a) System design integration including the preparation of motion compensation performance specifications.
- (b) Maison and design follow to assure overall system compatibility.
- (c) A mechanical preliminary design study for antenna angle control and design of servo installation on the radar frame.

25 YEAR RE-REVIEW

Attn: ASZ-5

-2-

November 13, 1962

The effort quoted for breadboard antenna stabilization and its evaluation quoted under Item 5, Section B, Flight Test, of Reference (a) is not affected by this proposal.

The performance specification has been developed based on several conferences with interested parties and is forwarded as Enclosure (1) for your review and consideration.

Our quotation for performing the effort outlined above is \$36,006 total estimated cost, and \$2,520 fixed fee. Enclosure (1) is an analysis of this quotation. Since this effort would replace that quoted under Item 1, Section B of Reference (a) for \$142,283 total estimated cost, the net reduction in total Contract Cost would be \$106,277.

Based on the fee negotiated for the SOARD Extension, the prorated fee for the \$142,283 total cost being deleted is \$8,878; therefore the net reduction in fee would be this figure less \$2,520 or \$6,358.

Technical coordination with interested groups is continuing pending your decision as to source for the motion compensation hardware. We have for the moment held work on its detailed design and fabrication as authorized by Amendment No. 13. If you adopt the proposal outlined herein, we will be glad to discuss the contractual arrangements at your convenience. However, because we are currently holding up authorized work which you may later procure elsewhere, an early decision on this proposal is desirable.

Very truly yours, WESTINGHOUSE ELECTRIC CORPORATION

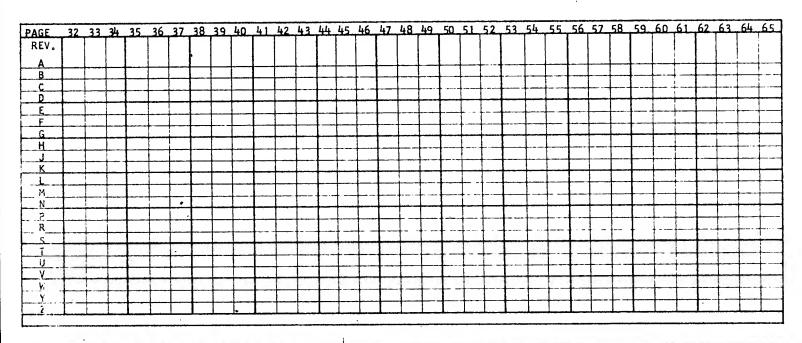
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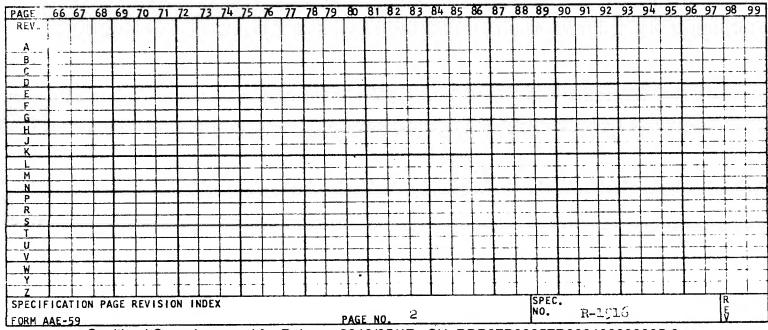
Project Liaison Marketing Department

RWE:sf

Sanitized Copy Approved for Release 2010/05/17: CIA-RDP67B00657R000100090005-6 FORM AAE-54A Westinghouse ELECTRIC CORPORATION
AIR ARM DIVISION BALTIMORE MD. U. BALTIMORE MD. U.S.A. ARCHITA ANGLE AND MOTION COMPERSATION (FOLLOWER VERSION) 3,4,5,5 11-7-62 A REV. LETTER DATE CHANGE ORDER NO. PAGES AFFECTED APPROVED REVISIONS ORIGINAL CHECKED BY PREPARED BY STATT APPROVED APPR APPROVED APPROVED DATE TOP DWG SPEC. NO. SHEET 1 OF ? SHEETS 11-7-62 R-1916

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The purpose of this specification is to describe the functional units necessary to achieve compensation for aircraft motion. Section 1.0 includes the roll stabilized platform—and related electronics to achieve compensated cross track acceleration of no more than 2 mill g or 1/16 wavelength, whichever is the more severe limitation at a particular frequency of disturbance. Section 2.0 includes the electronics for antenna positioning in the yaw axis to maintain the beam center within 2 milliradians of the intended pointing direction independently of aircraft motion in pitch and yaw. The environmental limitations are also included.

# 1.0 CROSS TRACK VELOCITY COMPENSATION

See Figure 1

### 1.1 Roll Stabilized Platform

	1.1.1	Outline limitation	Figure 2
	1.1.2	Roll axis alignment to aircraft	1°
	1.1.3	Accelerometer positioning relative to line of sight.	l ft.
	1.1.4	Accelerometer depression in roll	29° ±1°
	1.1.5	Maximus roll, rate	10°/sec.
	1.1.6	Aleximan roll acceleration	50°/sec <sup>2</sup>
	1.1.7	Positioning accuracy	.l milliradian
	1.1.3	Operating temperature range	+100°F to 300°F
	1.1.9	Maximum temperature range	-54°F to +300°F
	1.1.10	Unattended service life	1000 hrs.
1.2	Integr	ator and Leiwork	
	1.2.1	Maximum velocity	50 ft/sec
	1.2.2	Velocity resolution .	.Ol ft/sec
	1.2.3	Linearity	1,5
	1.2.4	Idealized network response	

$$F(s) = \frac{2 \Upsilon_1 s (1 + 1/2 \Upsilon_1 s)}{(1 + \Upsilon_1 s)^2} \times \frac{(1 + 3 \Upsilon_2 s)}{(1 + \Upsilon_2 s)^3}$$

$$T_1 = 63.0 \text{ sec}$$

$$\Upsilon_2 = .0106 \, \text{sec}$$

## 1.3 Frequency Off-Set Generator

- 1.3.1 Frequency mange
- 1.3.2 Linear voltage range
- 1.3.3 Frequency resolution
- 1.3.4 Linearity
- 1.3.5 Frequency sensitivity
- 1.3.6 Input impedance
- 1.3.7 Operating temperature range
- 1.3.3 Paximum te monuture
- I . J . C I PARLIMENT OF MALES

### 1.4 Accelerometer

- 1.4.1 Maximum acceleration
- 1.4.2 Resolution
  - 1.4.3 Linearity
- 1.4.4 Upper frequency limit
- 1.4.5 Operating temperature range
- 1.4.5 Maximum te merature runge

+200 cps to+600 cps

- +2.5 volt to-2.5v
- .2 ft/sec
- 1,5
- 330 cps/volt
- 50k olms
- +80° to +120°F
- -54° to +120°F

### 1 G

- l milli G
- 20 cps

.1.,

- 100° to 300°F
- ~54° to 300°F



2.0	AHGLE	COMPENSATION

Figure 1

 $\cdot 2.1$ Open loop antenna pointing error overall ±.6° (3**5**)

2.2 Antenna open loop response to aircraft notion

- 4 cps
- 2.3 Antenna system sensitivity at the input to the antenna follow serve.
- 1 degree/volt
- 2.4 Summing point shall be capable of accepting a signal from the doppler tracker (output impedance < 500 ~) and summing it with the open loop contents with unity win. ₩.
- 2.5 Open ting temperature range.

+80° +120°F

2.7 Maximum temperature runge -54° +140°F

- 2.8 Position potentio eter
  - 2.8.1 Operating temperature range

100°F to 450°F

\* 2.5 The dop, ler frequency tracker will close the autenma gointing loop at low frequencies with a pain in excess of a volt/ke and with unity thin at 1/10 cps.

# 3.0 CEITERAL

- 3.1 The environmental conditions except temperature and detailed in R-1011.
- 3.2 In the event of conflict between this document and any MIL Specification this document shall govern.

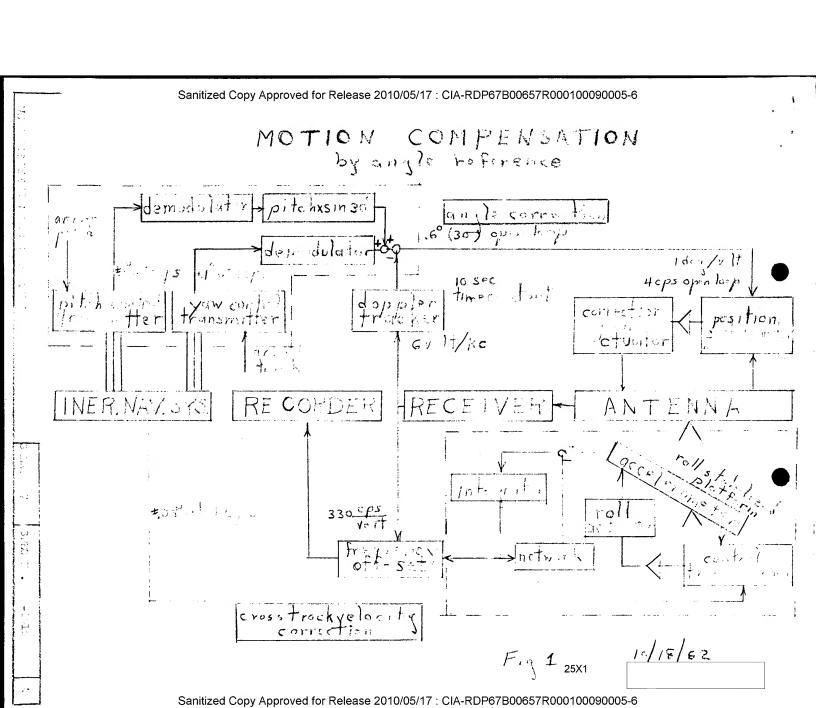
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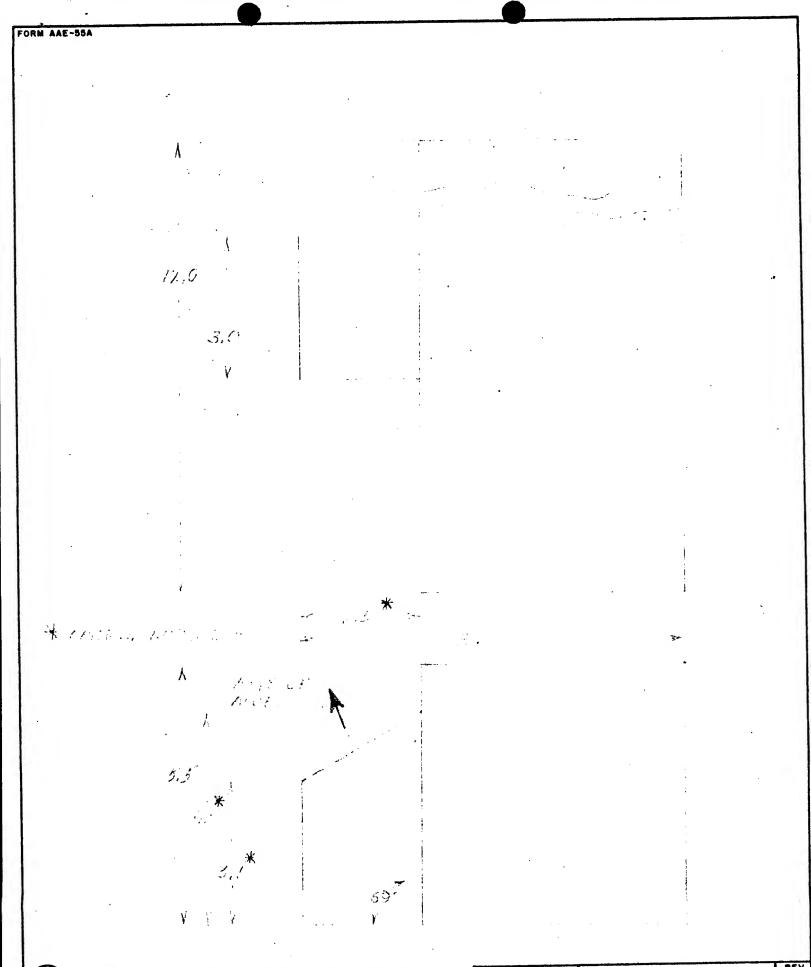
Westinghouse ELECTRIC CORPORATION
AIR ARM DIVISION BALTIMORE MD. U.S.A.

SHEET 6

SPEC. R-1916

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Westinghouse ELECTRIC CORPORATION
BALTIMORE MD. U.S.A.

SHEET {

SPEC.

R-1916

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Motion Compensati	ion System Investig	stion. Pollo	QUANTITY	AT	AMOUNT
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	LABOR ( 3.055 HOURS)				xxxxx
C. ENGINEERING	OVERHEAD			\$ 15,020	xxxxx
D. OTHER (SCHEE		Travel		12,289	xxxxx
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AAN-45196-20 - 13 November 1962

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Support & Evaluation	1,400	\$ 4.99	\$3.82	\$ 12,334
Noch. Besign & Development	795	5.10	3.72	7,004

NOTE: Engineering Labor Adjustment of 8.9% to be explicit to show rates

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Support & Evaluation	600	\$ 4.99	\$3.8e	\$ 5,286
Hoch. Design & Development	260	5.10	3.71	2,291

MOER: Engineering Labor Adjustment of 2.9% to be applied to show rates.

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NAME CONTRACTOR	etric Corportio	n - Air Arm Div	rision	PRIME SUB	7
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P.O. Box 746					
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B. ENGINEERING	3.077	(RS)		\$ 15,020	xxxxx
C. ENGINEERING				12.289	x
D. OTHER (SCHEE		Travel		4.535	xxxxx
	ENGINEERING COST			xxxxx	\$31.844
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11. TOTAL COST (SUM (	OF LINES 5 THRU 10)				
12.					36,006
13. OPERATING PROFIT	OR FIXED FEE				
14.					2,520
15.					
16. TOTAL ESTIMATED C	OST INCLUDING FIXED	FEE - COST TYPE C	ONTRACTS		1
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18.					
19.	<u> </u>				
20.		· · ·			
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AAN-45196-20 - 13 November 1962

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	Resident	Saler Rate	Overhead Rate	Labor and Overhead Dollars
Support & Svaluation	1,400	\$ 4.99	\$3.62	\$ 12,334
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MUTE: Engineering Labor Adjustment of 0.9% to be applied to show rates

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MOTE: Engineering Labor Adjustment of 2.9% to be applied to above rates.

DWG

11-7-62

SPEC. NO.

R-1916

The purpose of this specification is to describe the functional units necessary to achieve compensation for direcaft motion. Section 1.0 includes the roll stabilized platform—and related electronics to achieve compensated cross track acceleration of no more than 2 mill g or 1/16 wavelength, whichever is the more severe limitation at a particular frequency of disturbance. Section 2.0 includes the electronics for antenna positioning in the yaw axis to maintain the beam center within 2 milliradians of the intended pointing direction independently of aircraft motion in pitch and yaw. The environmental limitations are also included.

# 1.0 CROSS TRACK VELOCITY COMPENSATION

See Figure 1

# 1.1 Roll Stabilized Flatform

	1.1.1	Outline Limitation	Figure 2
	1.1.2	Roll axis alignment to aircraft	1°
	1.1.3	Accelerometer positioning relative to line of sight.	1 ft.
•	1.7.4	Accelerometer depression in roll	29° ±1°
	1.1.5	Maximum roll rate	10°/sec.
	1.1.5	Maximum roll acceleration	50°/sec <sup>2</sup>
	1.1.7	Fositioning accuracy	.l milliradian
	1.1.3	Operating temperature range	4100°F to 300°F
	1.1.9	Maximum temperature range	-5)4°F to +300°F
	1.1.10	Unattended service life	1.000 hrs.
1.2	Integr	ator and Network	
	1.2.1	Maximum velocity	50 ft/sec
	1.2.2	Velocity resolution .	.Ol ft/sec
	1.2.3	Linearity	15



Westinghouse ELECTRIC CORPORATION
BALTIMORE MD. U.S.A.

1.2.4 Idealized network response

SHEET

SPEC. NO.

R-1916

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$$F(s) = \frac{2 \Upsilon_1 s (1 + 1/2 \Upsilon_1 s)}{(1 + \Upsilon_1 s)^2} \times \frac{(1 + 3 \Upsilon_2 s)}{(1 + \Upsilon_2 s)^3}$$

- 1.3 Frequency Off-Set Generator
  - 1.3.1 Frequenc, range
  - 1.3.2 Linear voltage range
  - 1.3.3 Frequency resolution
  - 1.3.4 Linearity
  - 1.3.5 Frequency sensitivity
  - 1.3.5 Imput impedance
  - 1.3.7 Operating temperature range

  - 1.3.8 Maximum te merature
- 1.4 Accelerometer
  - 1.4.1 Maximum acceleration
  - 1.4.2 Resolution
    - 1.4.3 Linearity
    - 1.4.4 Upper frequency limit
    - 1.4.5 Operating temperature range
    - 1.4.5 Maximum temperature range

- +200 cps to+600 cps
- +2.5 volt to-2.5v
- .2 ft/sec
- 1%
- 330 cps/volt
- 50k ohma
- +30° to +120°F
- -54° to +120°F
- 1 G
- 1 milli G
- .1/2
- 20 cps
- 100° to 300°F
- -54° to 300°F



2.0 AUGLE	COMPENSATION
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Figure 1

· 2.1 Open loop antenna pointing error overall

±.6° (3**0**)

2.2 Antenna open loop response to aircraft motion

4 cps

2.3 Interna system sensitivity at the input to the antenna follow serve.

1 degree/wolt

- 2.4 Summing point shall be capable of accepting a signal from the doppler tracker (output impedance < 500 ~) and summing it with the open loop commands with unit; gain.
- 2.6 Operating temperature range.

+80° +120°F

2.7 Maximum temperature range

-54° +140°F

- 2.8 Position potention eter
  - 2.8.1 Operating temperature range

100°F to 450°F

\* 2.5 The dopplor frequency tracker will close the antenna pointing loop at low frequencies with a gain in excess of a volt/ke and with unit, gain at 1/10 eps.



Westinghouse ELECTRIC CORPORATION
BALTIMORE MD. U.S.A.

SHEET 5

SPEC. NO.

R-1,16

# 3.0 GENERAL

- 3.1 The environmental conditions except temperature and detailed in R-1811.
- 3.2 In the event of conflict between this document and any MIL Specification this document shall govern.

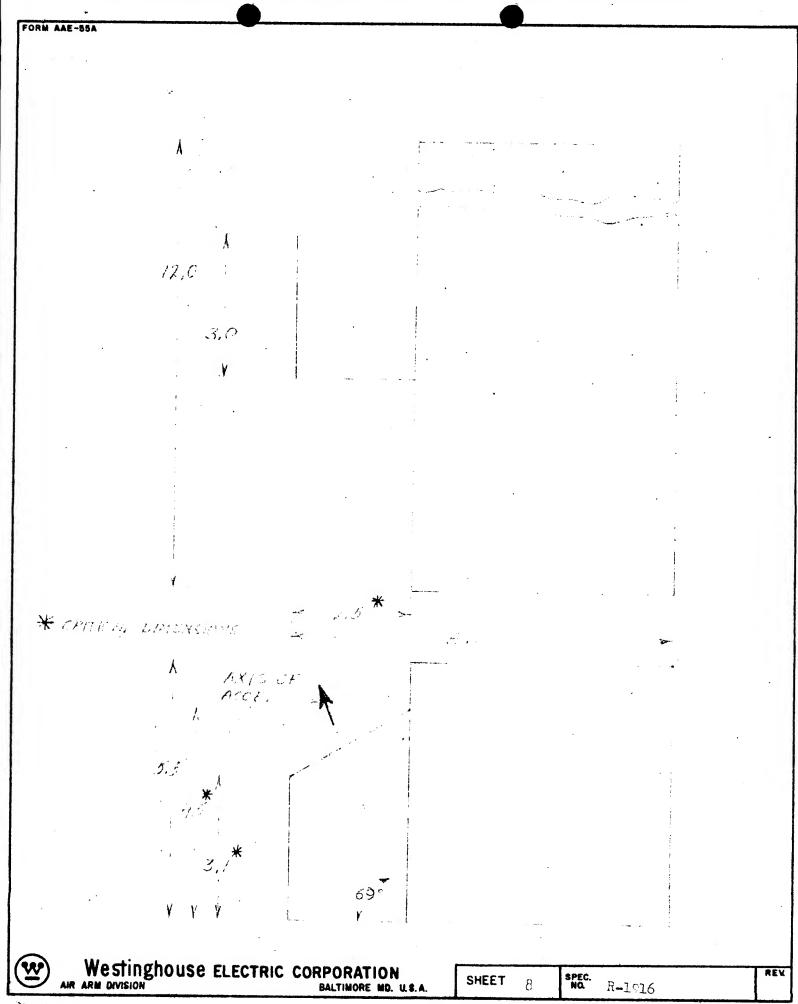
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Westinghouse ELECTRIC CORPORATION
BALTIMORE MD. U.S.A.

SHEET 6

SPEC.

R-1916



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